

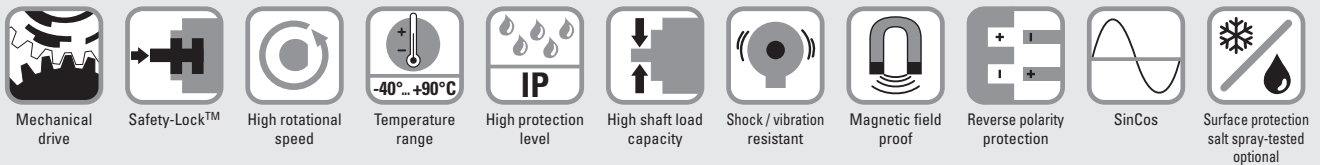
Absolute encoders – multiturn

Standard mechanical multiturn, optical	Sendix 5863 / 5883 (shaft / hollow shaft)	SSI / BiSS
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The Sendix 5863 and 5883 multiturn encoders with SSI or BiSS interface and optical sensor technology can achieve a resolution of max. 29 bits.

A through hollow shaft up to 14 mm and a blind hollow shaft up to 15 mm are available, as well as versions with additional SinCos or RS422 incremental track.



Reliable

- Tried-and-tested in applications with the highest demands, such as in wind energy or mobile automation.
- Absolutely reliable operation in areas with strong magnetic fields, thanks to mechanical gear with optical sensor technology.
- Rugged die-cast housing, remains sealed even in harsh everyday use.
- -40°C ... +90°C: use in wide temperature range and protection IP67.

Versatile

- Available with SSI or BiSS interface and combined with SinCos incremental signals.
- The right fixing solution or type of connection available for every application.
- SET button and LED for simple start-up.

Absolute encoders multiturn

Order code Shaft version

8.5863	.	<u>X</u> <u>X</u> <u>X</u> <u>X</u>	.	<u>X</u> <u>X</u> <u>2</u> <u>X</u>
Type		a b c d		e f g h

If for each parameter of an encoder the underlined preferred option is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.



a Flange

- 1 = clamping flange, IP65 ø 58 mm [2.28"]
 - 3 = clamping flange, IP67 ø 58 mm [2.28"]
 - 2 = synchro flange, IP65 ø 58 mm [2.28"]
 - 4 = synchro flange, IP67 ø 58 mm [2.28"]
 - 5 = square flange, IP65 □ 63.5 mm [2.5"]
 - 7 = square flange, IP67 □ 63.5 mm [2.5"]
-
- 6 = servo flange, IP65 ø 63.5 mm [2.5"]¹⁾
 - 8 = servo flange, IP67 ø 63.5 mm [2.5"]¹⁾

b Shaft (ø x L), with flat

- 1 = 6 x 10 mm [0.24 x 0.39"]²⁾
- 2 = 10 x 20 mm [0.39 x 0.79"]³⁾
- 3 = 1/4" x 7/8"
- 4 = 3/8" x 7/8"

c Interface / power supply

- 1 = SSI, BiSS / 5 V DC
- 2 = SSI, BiSS / 10 ... 30 V DC
- 3 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC
- 4 = SSI, BiSS + 2048 ppr. SinCos / 10 ... 30 V DC
- 5 = SSI, BiSS / 5 V DC, with sensor output
- 6 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC, with sensor output
- 7 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 5 V DC
- 8 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 10 ... 30 V DC
- 9 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 5 V DC, with sensor output

d Type of connection

- 1 = axial cable, 1 m [3.28"] PVC
 - A = axial cable, special length PVC *)
 - 2 = radial cable, 1 m [3.28"] PVC
 - B = radial cable, special length PVC *)
 - 3 = axial M23 connector, 12-pin
 - 4 = radial M23 connector, 12-pin
 - 5 = axial M12 connector, 8-pin⁴⁾
 - 6 = radial M12 connector, 8-pin⁴⁾
- *) Available special lengths (connection types A, B):
2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21"]
order code expansion .XXXX = length in dm
ex.: 8.5863.112A.G323.0030 (for cable length 3 m)

e Code

- B = SSI, binary
- C = BiSS, binary
- G = SSI, gray

f Resolution⁵⁾

- A = 10 bit ST + 12 bit MT
- 1 = 11 bit ST + 12 bit MT
- 2 = 12 bit ST + 12 bit MT
- 3 = 13 bit ST + 12 bit MT
- 4 = 14 bit ST + 12 bit MT
- 7 = 17 bit ST + 12 bit MT

Optional on request

- Ex 2/22
- surface protection salt spray tested
- other singleturn resolutions

g Inputs / outputs⁵⁾

- 2 = SET, DIR input additional status output

h Options (service)

- 1 = no option
- 2 = status LED
- 3 = SET button and status LED

1) US version.

2) Preferred type only in conjunction with flange type 2.

3) Preferred type only in conjunction with flange type 1.

4) Only in conjunction with interface type 1 and 2.

5) Resolution, preset value and counting direction factory-programmable.

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Order code Hollow shaft	8.5883 Type	.XXXXX.XX2X a b c d e f g h	If for each parameter of an encoder the <u>underlined preferred option</u> is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.				
a Flange 1 = with spring element, long, IP65 2 = with spring element, long, IP67 3 = with stator coupling, IP65 ø 65 mm [2.56"] 4 = with stator coupling, IP67 ø 65 mm [2.56"] <u>5 = with stator coupling, IP65 ø 63 mm [2.48"]</u> 6 = with stator coupling, IP67 ø 63 mm [2.48"]	b Hollow shaft 3 = ø 10 mm [0.39"] <u>4 = ø 12 mm [0.47"]</u> 5 = ø 14 mm [0.55"] 6 = ø 15 mm [0.59"] – blind hollow shaft 8 = ø 3/8" 9 = ø 1/2"	c Interface / power supply 1 = SSI, BiSS / 5 V DC <u>2 = SSI, BiSS / 10 ... 30 V DC</u> 3 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC 4 = SSI, BiSS + 2048 ppr. SinCos / 10 ... 30 V DC 5 = SSI, BiSS / 5 V DC, with sensor output 6 = SSI, BiSS + 2048 ppr. SinCos / 5 V DC, with sensor output 7 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 5 V DC 8 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 10 ... 30 V DC 9 = SSI, BiSS + 2048 ppr. RS422 (TTL-comp.) / 5 V DC, with sensor output	d Type of connection 2 = radial cable, 1 m [3.28'] PVC B = radial cable, special length PVC *) <u>E = tangential cable, 1 m [3.28'] PVC</u> F = tangential cable, special length PVC *) <u>4 = radial M23 connector, 12-pin</u> 6 = radial M12 connector, 8-pin ²⁾	e Code B = SSI, binary C = BiSS, binary <u>G = SSI, gray</u>	f Resolution ¹⁾ A = 10 bit ST + 12 bit MT 1 = 11 bit ST + 12 bit MT 2 = 12 bit ST + 12 bit MT <u>3 = 13 bit ST + 12 bit MT</u> 4 = 14 bit ST + 12 bit MT 7 = 17 bit ST + 12 bit MT	g Inputs / outputs ¹⁾ <u>2 = SET, DIR input</u> additional status output	h Options (service) 1 = no option 2 = status LED <u>3 = SET button and status LED</u>
*) Available special lengths (connection types B, F): 2, 3, 5, 8, 10, 15 m [5.56, 9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.5883.542B.G323.0030 (for cable length 3 m)							
Optional on request - Ex 2/22 (not for type of connection E, F) - surface protection salt spray tested - other singleturn resolutions							

Mounting accessory for shaft encoders		Order no.
Coupling	bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"]	8.0000.1102.0606
	bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]	8.0000.1102.1010
Mounting accessory for hollow shaft encoders		Order no.
Cylindrical pin, long for torque stops	with fixing thread 	8.0010.4700.0000
Connection technology		Order no.
Connector, self-assembly (straight)	M12 female connector with coupling nut	05.CMB 8181-0
	M23 female connector with coupling nut	8.0000.5012.0000
Cordset, pre-assembled	M12 female connector with coupling nut, 2 m [6.56'] PVC cable	05.00.6041.8211.002M
	M23 female connector with coupling nut, 2 m [6.56'] PVC cable	8.0000.6901.0002.0031

Further accessories can be found in the accessories section or in the accessories area of our website at: www.kuebler.com/accessories.
Additional connectors can be found in the connection technology section or in the connection technology area of our website at: www.kuebler.com/connection_technology.

1) Resolution, preset value and counting direction factory-programmable.
2) Only in conjunction with interface type 1 and 2.

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Technical data

Mechanical characteristics

Maximum speed shaft version		
IP65 up to 70°C [158°F]	12000 min ⁻¹ , 10000 min ⁻¹ (continuous)	
IP65 up to T _{max}	8000 min ⁻¹ , 5000 min ⁻¹ (continuous)	
IP67 up to 70°C [158°F]	11000 min ⁻¹ , 9000 min ⁻¹ (continuous)	
IP67 up to T _{max}	8000 min ⁻¹ , 5000 min ⁻¹ (continuous)	
Maximum speed hollow shaft version		
IP65 up to 70°C [158°F]	9000 min ⁻¹ , 6000 min ⁻¹ (continuous)	
IP65 up to T _{max}	6000 min ⁻¹ , 3000 min ⁻¹ (continuous)	
IP67 up to 70°C [158°F]	8000 min ⁻¹ , 4000 min ⁻¹ (continuous)	
IP67 up to T _{max}	4000 min ⁻¹ , 2000 min ⁻¹ (continuous)	
Starting torque at 20°C [68°F]		
IP65	< 0.01 Nm	
IP67	< 0.05 Nm	
Mass moment of inertia		
shaft version	4.0 x 10 ⁻⁶ kgm ²	
hollow shaft version	7.0 x 10 ⁻⁶ kgm ²	
Load capacity of shaft		
radial	80 N	
axial	40 N	
Weight		
	approx. 0.45 kg [15.87 oz]	
Protection acc. to EN 60529		
housing side	IP67	
shaft side	IP65, opt. IP67	
Working temperature range		
	-40°C ... +90°C [-40°F ... +194°F] ¹⁾	
Material		
shaft/hollow shaft	stainless steel	
flange	aluminium	
housing	zinc die-cast	
cable	PVC	
Shock resistance acc. to EN 60068-2-27		
	2500 m/s ² , 6 ms	
Vibration resistance acc. to EN 60068-2-6		
	100 m/s ² , 55 ... 2000 Hz	

Electrical characteristics

Power supply	5 V DC (+5%) or 10 ... 30 V DC
Current consumption (no load)	5 V DC max. 80 mA 10 ... 30 V DC max. 50 mA
Reverse polarity protection of the power supply	yes (at 10 ... 30 V DC)
Short circuit proof outputs	yes ²⁾
UL approval	file 224618
CE compliant acc. to	EMC guideline 2004/108/EC RoHS guideline 2011/65/EU

1) Cable version: -30°C ... +75°C [-22°F ... +167°F].
2) Short circuit to 0V or to output, one channel at a time, power supply correctly applied.

SSI interface

Output driver	RS485 transceiver type
Permissible load / channel	max. +/- 20 mA
Signal level	HIGH typ. 3.8 V LOW at I _{Load} = 20 mA typ. 1.3 V
Resolution singleturn	10 ... 14 bit and 17 bit
Number of revolutions (multiturn)	4096 (12 bit)
Code	binary or gray
SSI clock rate	50 kHz ... 2 MHz
Monoflop time	≤ 15 μs
Note: If the clock starts cycling within the monoflop time, a second data transfer starts with the same data. If the clock starts cycling after the monoflop time, the data transfer starts with the new values. The update rate is dependent on the clock speed, data length and monoflop-time.	
Data refresh rate	ST resolution ≤ 14 bit ≤ 1 μs ST resolution ≥ 15 bit 4 μs

BiSS interface

Resolution singleturn	10 ... 14 bit and 17 bit
Number of revolutions (multiturn)	4096 (12 bit)
Code	binary
Clock rate	50 kHz ... 10 MHz
Max. update rate	< 10 μs, depends on the clock rate and the data length
Data refresh rate	≤ 1 μs
Note:	
– bidirectional, factory programmable parameters are: resolution, code, direction, alarms and warnings	
– CRC data verification	

SET input or SET button

Input	active HIGH
Input type	comparator
Signal level	HIGH min: 60 % of +V (power supply) max: +V LOW max: 25 % of +V (power supply)
Input current	< 0.5 mA
Min. pulse duration (SET)	10 ms
Timeout after SET signal	14 ms
Response time (DIR input)	1 ms

The encoder can be set to zero at any position by means of a HIGH signal on the SET input or by pressing the optional SET button (with a pencil, ball-point pen or similar). Other preset values can be factory-programmed. The SET input has a signal processing time of approx. 1 ms. Once the SET function has been triggered, the encoder requires an internal processing time of approx. 15 ms before the new position data can be read. During this time the status output is at LOW.

Option incremental outputs (A/B), 2048 ppr

	SinCos	RS422 TTL compatible
Max. frequency -3dB	400 kHz	400 kHz
Signal level	1 V _{pp} (± 20%)	HIGH: min. 2.5 V LOW: max. 0.5 V
Short circuit proof	yes	yes

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Status output and LED	
Output driver	open collector, internal pull up resistor 22 kOhm
Permissible load	max. 20 mA
Signal level	HIGH: +V / LOW: < 1 V
Active	LOW
The optional LED (red) and the status output serve to display various alarm or error messages. In normal operation the LED is OFF and the status output is HIGH (open collector with int. pull up 22 kOhm).	
An active status output (LOW) displays: <ul style="list-style-type: none"> – sensor error, singleturn or multiturn (soiling, glass breakage etc.) – LED fault (failure or ageing) – over- or under-temperature 	
In the SSI mode, the fault indication can only be reset by switching off the power-supply to the device.	

DIR input
A HIGH signal switches the direction of rotation from the default cw to ccw. This function can also be factory-programmed to be inverted. If DIR is changed when the device is already switched on, then this will be interpreted as an error. The LED will come ON and the status output will switch to LOW.

Power-ON time
After Power-ON the encoder requires a time of approx. 150 ms before valid data can be read.

Terminal assignment

Interface	Type of connection	Features	Cable (isolate unused wires individually before initial start-up)
1, 2	1, 2, A, B, E, F	SET, DIR, Status	Signal: 0 V +V C+ C- D+ D- SET DIR Stat N/C N/C N/C \perp
			Cable colour: WH BN GN YE GY PK BU RD BK - - - shield
1, 2	3, 4	SET, DIR, Status	M23 connector
			Signal: 0 V +V C+ C- D+ D- SET DIR Stat N/C N/C N/C \perp
5	1, 2, A, B, E, F	SET, DIR, Status sensor output	Cable (isolate unused wires individually before initial start-up)
			Signal: 0 V +V C+ C- D+ D- SET DIR Stat N/C 0Vsens +Vsens \perp
5	3, 4	SET, DIR, Status sensor output	M23 connector
			Signal: 0 V +V C+ C- D+ D- SET DIR Stat N/C 0Vsens +Vsens \perp
3, 4, 7, 8	1, 2, A, B, E, F	SET, DIR, SinCos or incr. RS422	Cable (isolate unused wires individually before initial start-up)
			Signal: 0 V +V C+ C- D+ D- SET DIR A \bar{A} B \bar{B} \perp
3, 4, 7, 8	3, 4	SET, DIR, SinCos or incr. RS422	M23 connector
			Signal: 0 V +V C+ C- D+ D- SET DIR A \bar{A} B \bar{B} \perp
6, 9	1, 2, A, B, E, F	SinCos o. incr. RS422 sensor output	Cable (isolate unused wires individually before initial start-up)
			Signal: 0 V +V C+ C- D+ D- A \bar{A} B \bar{B} 0Vsens +Vsens \perp
6, 9	3, 4	SinCos o. incr. RS422 sensor output	M23 connector
			Signal: 0 V +V C+ C- D+ D- A \bar{A} B \bar{B} 0Vsens +Vsens \perp
1, 2	5, 6	SET, DIR	M12 connector
			Signal: 0 V +V C+ C- D+ D- SET DIR \perp
			Pin: 1 2 3 4 5 6 7 8 PH

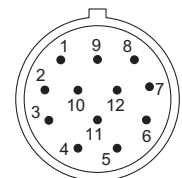
- +V: Encoder power supply +V DC
- 0 V: Encoder power supply ground GND (0 V)
- 0 Vsens / +Vsens: Using the sensor outputs of the encoder, the voltage present can be measured and if necessary increased accordingly.
- C+, C-: Clock signal
- D+, D-: Data signal
- A, \bar{A} : Incremental output channel A (cosine)
- B, \bar{B} : Incremental output channel B (sine)

- SET: SET input. The current position becomes defined as position zero.
- DIR: Direction input: If this input is active, output values are counted backwards (decrease) when the shaft is turning clockwise.
- Stat: Status output
- PH \perp : Plug connector housing (shield)

Top view of mating side, male contact base



M12 connector, 8-pin



M23 connector, 12-pin

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Dimensions shaft version

Dimensions in mm [inch]

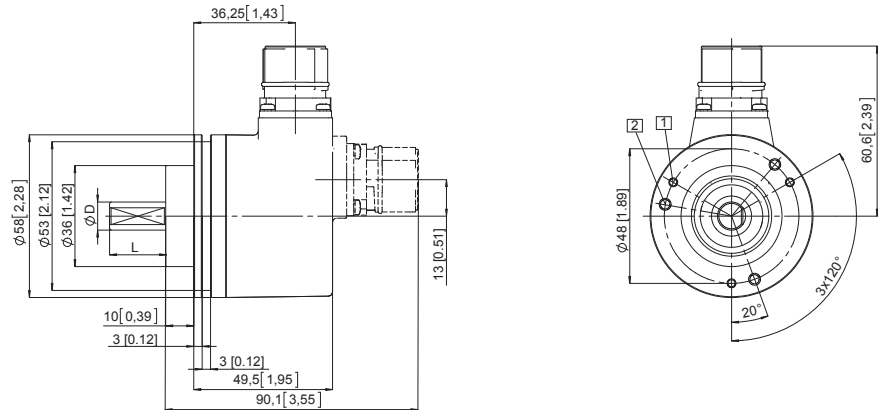
Clamping flange, $\varnothing 58$ [2.28]

Flange type 1 and 3

(drawing with M23 connector)

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep

D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7



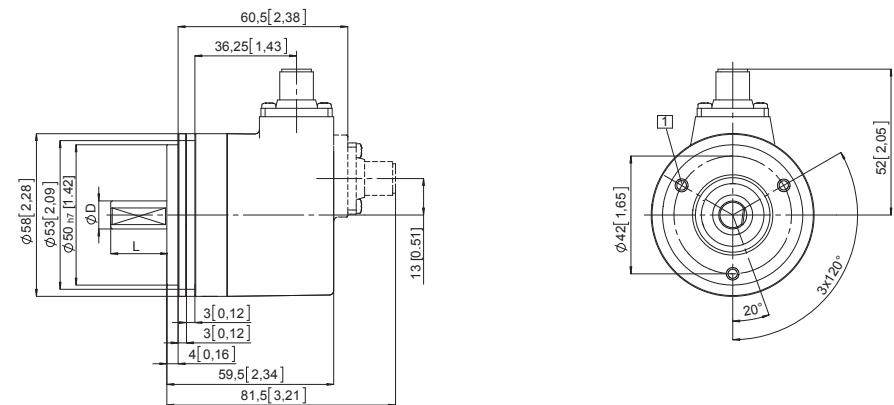
Synchro flange, $\varnothing 58$ [2.28]

Flange type 2 and 4

(drawing with M12 connector)

- 1 M4, 6 [0.24] deep

D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7

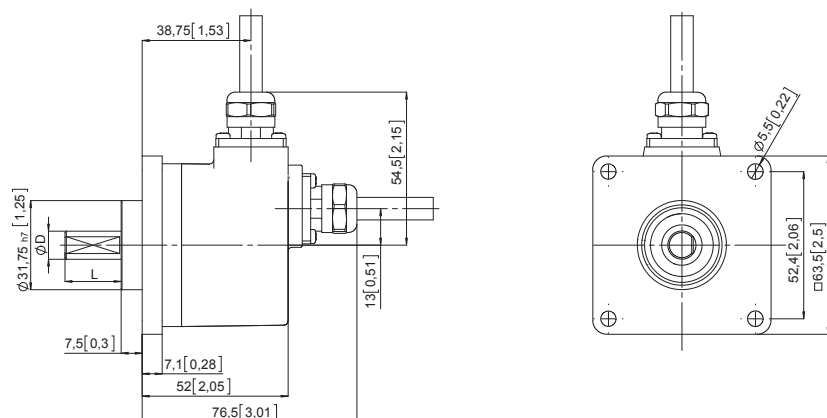


Square flange, $\square 63.5$ [2.5]

Flange type 5 and 7

(drawing with cable)

D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7



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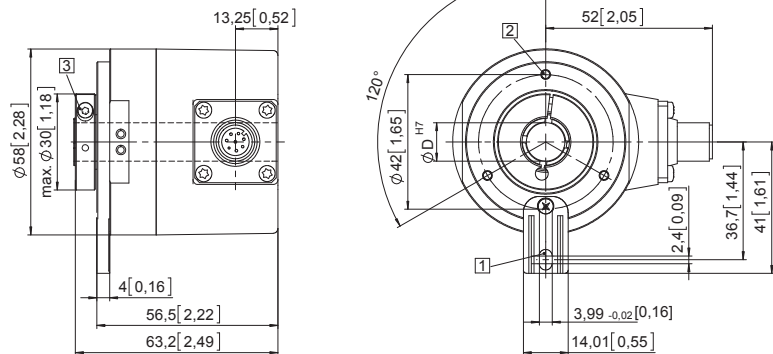
SSI / BiSS

Dimensions hollow shaft version

Dimensions in mm [inch]

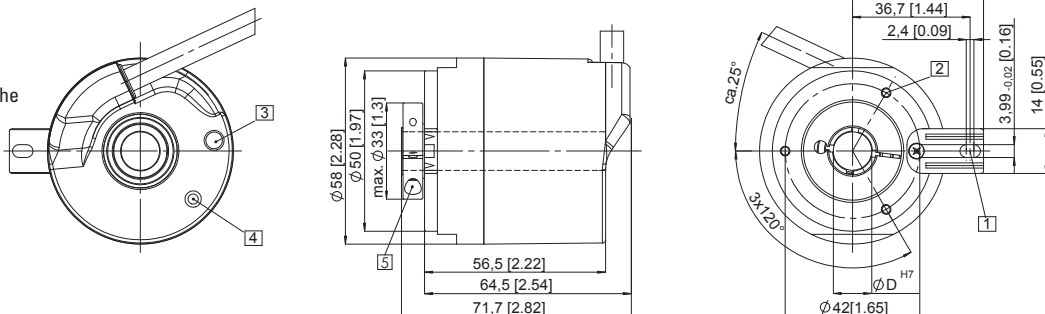
Flange with spring element, long Flange type 1 and 2 (drawing with M12 connector)

- 1 Torque stop slot, recommendation: cylindrical pin DIN 7, \varnothing 4 [0.16]
- 2 M3, 6 [0.24] deep
- 3 Recommended torque for the clamping ring 0.6 Nm



Flange with spring element, long Flange type 1 and 2 (drawing with tangential cable)

- 1 Torque stop slot, recommendation: cylindrical pin DIN 7, \varnothing 4 [0.16]
- 2 M3, 5.5 [0.21] deep
- 3 Status-LED
- 4 SET button
- 5 Recommended torque for the clamping ring 0.6 Nm



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Dimensions hollow shaft version

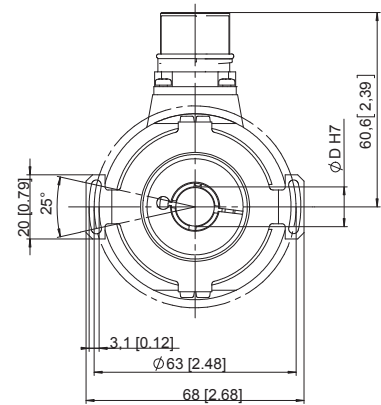
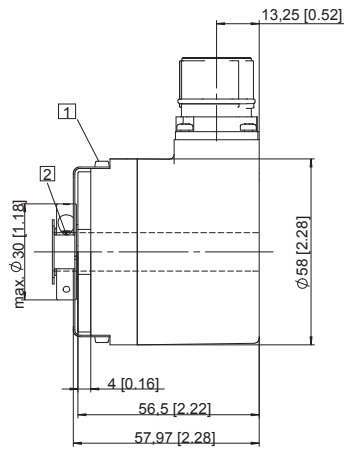
Dimensions in mm [inch]

Flange with stator coupling, \varnothing 63 [2.48]

Flange type 5 and 6

Pitch circle diameter for fixing screws 63 [2.48]
(drawing with M23 connector)

- 1 Fixing screws DIN 912 M3 x 8
(washer included in delivery)
- 2 Recommended torque for the
clamping ring 0.6 Nm

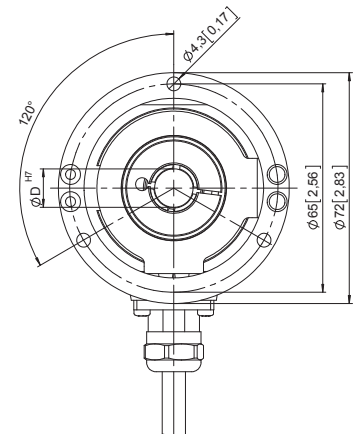
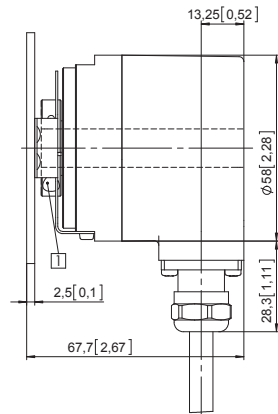


Flange with stator coupling, \varnothing 65 [2.56]

Flange type 3 and 4

Pitch circle diameter for fixing screws 65 [2.56]
(drawing with cable)

- 1 Recommended torque for the
clamping ring 0.6 Nm



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