

# Absolute encoders – multiturn

<b>Standard mechanical multiturn, optical</b>	<b>Sendix 5868 / 5888 (shaft / hollow shaft)</b>	<b>CANopen/CANopenLift</b>
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The Sendix multiturn encoders 5868 and 5888 with CANopen or CANopenLift interface and optical sensor technology are the right encoders for all CANopen or CANopenLift applications.

With a maximum resolution of 28 bits these encoders offer an optional additional RS422 incremental track with 2048 pulses.



Mechanical drive	Safety-Lock™	High rotational speed	Temperature range -40°...+80°C	High protection level IP	High shaft load capacity	Shock / vibration resistant	Magnetic field proof	Reverse polarity protection	Optical sensor	Surface protection salt spray-tested optional

## Reliable

- Tried-and-tested in applications with the highest demands, such as in mobile automation or medical technology.
- Ideal for use outdoors thanks to IP67 protection and wide temperature range from -40°C up to +80°C.

## Flexible

- Node address can be set via rotary switches or software.
- Baud rate and termination can be set via DIP switches or software.
- With bus terminal cover or fixed connection, as well as M12 connectors or cable connection.
- Universal scaling function.

Absolute encoders  
multiturn

<b>Order code</b>	<b>8.5868</b>	. <u>X</u> <u>X</u> <u>X</u> <u>X</u> . <u>XX</u> <u>2</u> <u>X</u>	If for each parameter of an encoder the <b>underlined preferred option</b> is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.	<b>10 by 10</b>						
<b>Shaft version</b>	Type	<table border="1" style="font-size: x-small; border-collapse: collapse;"> <tr> <td style="text-align: center;">a</td> <td style="text-align: center;">b</td> <td style="text-align: center;">c</td> <td style="text-align: center;">d</td> <td style="text-align: center;">e</td> <td style="text-align: center;">f</td> </tr> </table>	a	b	c	d	e	f		
a	b	c	d	e	f					

- a Flange**
- 1** = clamping flange, IP65 ø 58 mm [2.28"]
  - 3 = clamping flange, IP67 ø 58 mm [2.28"]
  - 2** = synchro flange, IP65 ø 58 mm [2.28"]
  - 4 = synchro flange, IP67 ø 58 mm [2.28"]
  - 5 = square flange, IP65 □ 63.5 mm [2.5"]
  - 7 = square flange, IP67 □ 63.5 mm [2.5"]

- b Shaft (ø x L), with flat**
- 1** = 6 x 10 mm [0.24 x 0.39"]<sup>1)</sup>
  - 2** = 10 x 20 mm [0.39 x 0.79"]<sup>2)</sup>
  - 3 = 1/4" x 7/8"
  - 4 = 3/8" x 7/8"

- c Interface / power supply**
- 2** = CANopen DS301 V4.02, 10 ... 30 V DC
  - 5** = CANopen DS301 V4.02, 10 ... 30 V DC
- with 2048 ppr incremental track (TTL-compatible)<sup>3)</sup>

- d Type of connection**
- removable bus terminal cover*
- 1 = radial cable gland
  - 2 = M12 connector**
- Fixed connection without bus terminal cover*
- A = radial cable, 2 m [6.56'] PVC
  - B = radial cable, special length PVC \*)
  - E = 1 x radial M12 connector, 5-pin
  - F = 2 x radial M12 connector, 5-pin
  - I = 1 x radial M23 connector, 12-pin
  - J = 2 x radial M23 connector, 12-pin
  - K = 1 x Sub-D connector, 9-pin
- \*) Available special lengths (connection type B): 3, 5, 8, 10, 15 m [9.84, 16.40, 26.25, 32.80, 49.21']  
order code expansion .XXXX = length in dm  
ex.: 8.5868.112B.2123.0030 (for cable length 3 m)

- e Fieldbus profile<sup>4)</sup>**
- 21** = CANopen encoder profile DS406 V3.2
  - 22 = CANlift DS417 V1.01

- f Options (service)**
- 2 = no options
  - 3 = SET button**
- Optional on request*
- Ex 2/22
  - surface protection salt spray tested

1) Preferred type only in conjunction with flange type 2.  
2) Preferred type only in conjunction with flange type 1.  
3) Only in conjunction with connection type 2.  
4) CAN parameters can also be factory pre-set.

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<b>Order code</b> <b>Hollow shaft</b>	<b>8.5888</b> Type	<b>.XXXX</b> a b c d	<b>.XX2X</b> e f	<p>If for each parameter of an encoder the <b>underlined preferred option</b> is selected, then the delivery time will be 10 working days for a maximum of 10 pieces. Qts. up to 50 pcs. of these types generally have a delivery time of 15 working days.</p>
<p><b>a Flange with torque stop</b> 1 = with spring element, long, IP65 2 = with spring element, long, IP67 3 = with stator coupling, IP65 ø 65 mm [2.56"] 4 = with stator coupling, IP67 ø 65 mm [2.56"] <b>5 = with stator coupling, IP65 ø 63 mm [2.48"]</b> 6 = with stator coupling, IP67 ø 63 mm [2.48"]</p> <p><b>b Blind hollow shaft</b> 3 = ø 10 mm [0.39"] <b>4 = ø 12 mm [0.47"]</b> 5 = ø 14 mm [0.55"] 6 = ø 15 mm [0.59"] 8 = ø 3/8" 9 = ø 1/2"</p> <p><b>c Interface / power supply</b> <b>2 = CANopen DS301 V4.02, 10 ... 30 V DC</b> <b>5 = CANopen DS301 V4.02, 10 ... 30 V DC mit 2048 ppr incremental track (TTL-compatible) 1)</b></p>	<p><b>d Type of connection</b> <i>removable bus terminal cover</i> 1 = radial cable gland <b>2 = M12 connector</b> <i>Fixed connection without bus terminal cover</i> A = radial cable, 2 m [6.56'] PVC B = radial cable, special length PVC *) E = 1 x radial M12 connector, 5-pin F = 2 x radial M12 connector, 5-pin I = 1 x radial M23 connector, 12-pin J = 2 x radial M23 connector, 12-pin K = 1 x Sub-D connector, 9-pin</p> <p>*) Available special lengths (connection type B): 3, 5, 8, 10, 15 m [9.84, 16.40, 26.25, 32.80, 49.21'] order code expansion .XXXX = length in dm ex.: 8.5888.542B.2123.0030 (for cable length 3 m)</p>	<p><b>e Fieldbus profile 2)</b> <b>21 = CANopen encoder profile DS406 V3.2</b> 22 = CANlift DS417 V1.01</p> <p><b>f Options (service)</b> 2 = no options <b>3 = SET button</b></p> <p><i>Optional on request</i> - Ex 2/22 - surface protection salt spray tested</p>		

Mounting accessory for shaft encoders		Order no.
<b>Coupling</b>	bellows coupling ø 19 mm [0.75"] for shaft 6 mm [0.24"]	<b>8.0000.1102.0606</b>
	bellows coupling ø 19 mm [0.75"] for shaft 10 mm [0.39"]	<b>8.0000.1102.1010</b>
Mounting accessory for hollow shaft encoders		Order no.
<b>Cylindrical pin, long</b> for torque stops	<p>with fixing thread</p>	<b>8.0010.4700.0000</b>
Connection technology		Order no.
<b>Connector, self-assembly (straight)</b>	coupling M12 for bus in	<b>8.0000.5116.0000</b>
	connector M12 for bus out	<b>8.0000.5111.0000</b>
<b>Cordset, pre-assembled</b>	M12, for bus in, 6 m [19.68'] PVC cable	<b>05.00.6091.A211.006M</b>
	M12, for bus out, 6 m [19.68'] PVC cable	<b>05.00.6091.A411.006M</b>

Further accessories can be found in the accessories section or in the accessories area of our website at: [www.kuebler.com/accessories](http://www.kuebler.com/accessories).  
Additional connectors can be found in the connection technology section or in the connection technology area of our website at: [www.kuebler.com/connection\\_technology](http://www.kuebler.com/connection_technology).

1) Only in conjunction with connection type 2.  
2) CAN parameters can also be factory pre-set.

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## Technical data

### Mechanical characteristics

<b>Maximum speed</b>		
IP65 up to 70°C [158°F]	9000 min <sup>-1</sup> , 7000 min <sup>-1</sup> (continuous)	
IP65 up to T <sub>max</sub>	7000 min <sup>-1</sup> , 4000 min <sup>-1</sup> (continuous)	
IP67 up to 70°C [158°F]	8000 min <sup>-1</sup> , 6000 min <sup>-1</sup> (continuous)	
IP67 up to T <sub>max</sub>	6000 min <sup>-1</sup> , 3000 min <sup>-1</sup> (continuous)	
<b>Starting torque - at 20°C [68°F]</b>		
IP65	< 0.01 Nm	
IP67	< 0.05 Nm	
<b>Mass moment of inertia</b>		
shaft version	4.0 x 10 <sup>-6</sup> kgm <sup>2</sup>	
hollow shaft version	7.5 x 10 <sup>-6</sup> kgm <sup>2</sup>	
<b>Load capacity of shaft</b>		
radial	80 N	
axial	40 N	
<b>Weight</b>		
with bus terminal cover	approx. 0.57 kg [20.11 oz]	
with fixed connection	approx. 0.52 kg [18.34 oz]	
<b>Protection acc. to EN 60529</b>		
housing side	IP67	
shaft side	IP65, opt. IP67	
<b>Working temperature range</b>		
-40°C ... +80°C [-40°F ... +176°F] <sup>1)</sup>		
<b>Material</b>		
shaft/hollow shaft	stainless steel	
flange	aluminium	
housing	zinc die-cast	
cable	PVC	
<b>Shock resistance acc. to EN 60068-2-27</b>		
2500 m/s <sup>2</sup> , 6 ms		
<b>Vibration resistance acc. to EN 60068-2-6</b>		
100 m/s <sup>2</sup> , 55 ... 2000 Hz		

### Electrical characteristics

<b>Power supply</b>	10 ... 30 V DC
<b>Power consumption (no load)</b>	max. 100 mA
<b>Reverse polarity protection of the power supply</b>	yes
<b>UL approval</b>	file 224618
<b>CE compliant acc. to</b>	EMC guideline 2004/108/EC RoHS guideline 2011/65/EU

### Interface characteristics CANopen/CANopenLift

<b>Resolution singleturn</b>	1 ... 65536 (16 bit), scalable default: 8192 (13 bit)
<b>Number of revolutions (multiturn)</b>	max. 4096 (12 bit) scalable only via the total resolution
<b>Total resolution</b>	1 ... 268.435.456 (28 bit), scalable default: 33.554.432 (25 bit)
<b>Code</b>	binary
<b>Interface</b>	CAN high-speed acc. to ISO 11898, Basic- and Full-CAN CAN specification 2.0 B
<b>Protocol</b>	CANopen profile DS406 V3.2 with manufacturer-specific add-ons or CANlift profile DS417 V1.1
<b>Baud rate</b>	10 ... 1000 kbit/s can be set via DIP switches, software configurable
<b>Node address</b>	1 ... 127 can be set via rotary switches, software configurable
<b>Termination switchable</b>	can be set via DIP switches, software configurable

### Incremental track characteristics

<b>Output driver</b>	RS422 (TTL-compatible)
<b>Permissible load / channel</b>	max. +/- 20 mA
<b>Signal level</b>	HIGH typ. 3.8 V LOW typ. 1.3 V
<b>Short circuit proof outputs</b>	yes <sup>2)</sup>
<b>Resolution</b>	2048 ppr

### SET button (zero or defined value, option)

Protection against accidental activation.  
Button can only be operated with a ball-pen or pencil.

### Diagnostic LED (yellow)

**LED is ON with the following fault conditions**  
Sensor error (internal code or LED error) too low voltage, over-temperature

 Absolute encoders  
multiturn

1) Cable version: -30°C ... +75°C [-22°F ... +167°F].  
2) Short circuit to 0 V or to output, only one channel at a time, power supply correctly applied.

## Standard mechanical multiturn, optical

## Sendix 5868 / 5888 (shaft / hollow shaft)

## CANopen/CANopenLift

### General information about CANopen / CANopenLift

The CANopen encoders support the latest CANopen communication profile according to DS301 V4.02. In addition, device specific profiles such as encoder profile DS406 V3.2 and DS417 V1.1 (for lift applications) are available

The following operating modes may be selected: Polled Mode, Cyclic Mode, Sync Mode. Moreover, scale factors, preset values, limit switch values and many other additional parameters can be programmed via the CAN bus.

When switching the device on, all parameters are loaded from an EEPROM, where they were saved previously to protect them against power-failure.

The following output values may be combined in a freely variable way as PDO (PDO mapping): position, speed, acceleration as well as the status of the working area.

As competitively priced alternatives, encoders are also available with a connector or a cable connection, where the device address and baud rate can be changed and configured by means of the software. The models with bus terminal cover and integrated T-coupler allow for extremely simple installation: the bus and power supply can be easily connected via M12 connectors. The device address can be set via 2 rotary hex switches. Furthermore, another DIP switch allows for the setting of the baud rate and switching on a termination resistor. Three LEDs located on the back indicate the operating or fault status of the CAN bus, as well as the status of an internal diagnostic.

### Universal Scaling Function

At the end of the physical resolution of an encoder, **when scaling is active**, an error appears if the division of the physical limit (GP\_U) by the programmed total resolution (TMR) does not produce an integer.

The Universal Scaling Function remedies this problem.

### CANopen communication profile DS301 V4.02

Among others, the following functionality is integrated.

- Class C2 functionality.
- NMT slave.
- Heartbeat protocol.
- High resolution sync protocol.
- Identity object.
- Error behaviour object.
- Variable PDO mapping.
- Self-start programmable (power on to operational).
- 3 Sending PDO's.
- Node address, baud rate and CANbus.
- Programmable termination.

### CANopen Encoder Profile DS406 V3.2

The following parameters can be programmed:

- Event mode.
- Units for speed selectable (steps/sec or min<sup>-1</sup>).
- Factor for speed calculation (e.g. circumference of measuring wheel).
- Integration time for the speed value from 1 ... 32.
- 2 working areas with 2 upper and lower limits and the corresponding output states.
- Variable PDO mapping for position, speed, work area status.
- Extended failure management for position sensing with integrated temperature control.
- User interface with visual display of bus and failure status - 3 LED's.
- Optional - 32 CAMs programmable.
- Customer-specific memory - 16 Bytes.

### CANopen Lift Profile DS417 V1.1

Among others, the following functionality is integrated:

- Car position unit.
- 2 virtual devices.
- 1 virtual device delivers the position in absolute measuring steps (steps).
- 1 virtual device delivers the position as an absolute travel information in mm.
- Lift number programmable.
- Independent setting of the node address in relation with the CAN identifier.
- Factor for speed calculation (e.g. measuring wheel periphery).
- Integration time for speed value of 1...32.
- 2 work areas with 2 upper and lower limits and the corresponding output states.
- Variable PDO mapping for position, speed, acceleration, work area status.
- Extended failure management for position sensing with integrated temperature control.
- User interface with visual display of bus and failure status - 3 LED's.
- "Watchdog controlled" device.

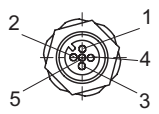
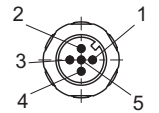
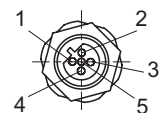
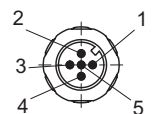
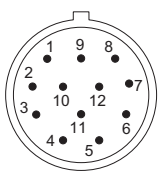
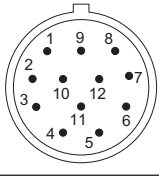
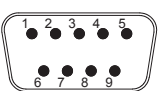
All profiles stated here: Key-features

The object 6003h "Preset" is assigned to an integrated key, accessible from the outside.

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## Terminal assignment

Interface	Type of connection	Cable gland (bus terminal cover with terminal box)										
2, 5	1	Bus OUT					Bus IN					
		Signal:	CAN_GND	CAN_L	CAN_H	0 V power supply	+V power supply	0 V power supply	+V power supply	CAN_L	CAN_H	CAN_GND
		Abbreviation:	CG	CL	CH	0 V	+V	0 V	+V	CL	CH	CG
Interface	Type of connection	Cable (isolate unused wires individually before initial start-up)										
2, 5	A, B	Bus IN										
		Signal:	0 V power supply	+V power supply	CAN_L	CAN_H	CAN_GND					
		Cable colour:	WH	BN	YE	GN	GY					
Interface	Type of connection	2 x M12 connector (3 x M12 connector with interface 5)										
2, 5	2, F	Bus OUT										
		Signal:	0 V power supply	+V power supply	CAN_L	CAN_H						CAN_GND
		Pin:	3	2	5	4	1					
		Bus IN										
		Signal:	0 V power supply	+V power supply	CAN_L	CAN_H						CAN_GND
		Pin:	3	2	5	4	1					
5	2	Incremental track										
		Signal:	A	$\bar{A}$	B	$\bar{B}$						0 V
		Pin:	1	2	3	4						5
Interface	Type of connection	1 x M12 connector										
2, 5	E	Bus IN										
		Signal:	0 V power supply	+V power supply	CAN_L	CAN_H						CAN_GND
		Pin:	3	2	5	4						1
Interface	Type of connection	2 x M23 connector										
2, 5	J	Bus OUT										
		Signal:	0 V power supply	+V power supply	CAN_L	CAN_H						CAN_GND
		Pin:	10	12	2	7						3
		Bus IN										
		Signal:	0 V power supply	+V power supply	CAN_L	CAN_H						CAN_GND
		Pin:	10	12	2	7						3
Interface	Type of connection	1 x M23 connector										
2, 5	I	Bus IN										
		Signal:	0 V power supply	+V power supply	CAN_L	CAN_H						CAN_GND
		Pin:	10	12	2	7						3
Interface	Type of connection	Sub-D connector										
2, 5	K	Bus IN										
		Signal:	0 V power supply	+V power supply	CAN_L	CAN_H						CAN_GND
		Pin:	6	9	2	7						3

 Absolute encoders  
multiturn

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**Sendix 5868 / 5888 (shaft / hollow shaft)**

**CANopen/CANopenLift**

## Dimensions shaft version, with removable bus terminal cover

Dimensions in mm [inch]

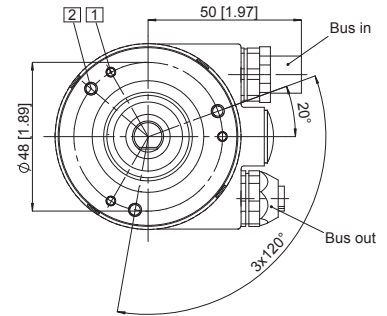
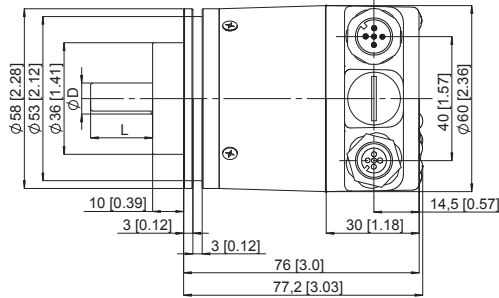
### Clamping flange, $\varnothing$ 58 [2.28]

#### Flange type 1 and 3

(drawing with 2 x M12 connector)

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep

D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7



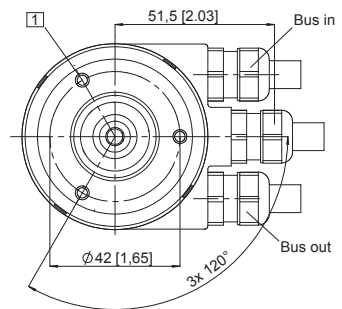
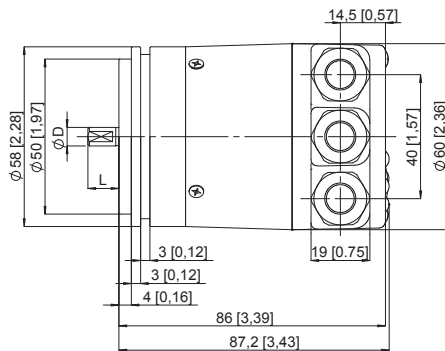
### Synchro flange, $\varnothing$ 58 [2.28]

#### Flange type 2 and 4

(drawing with cable)

- 1 M4, 6 [0.24] deep

D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7

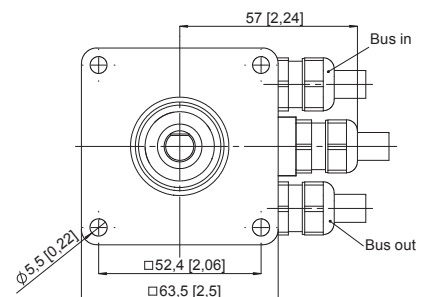
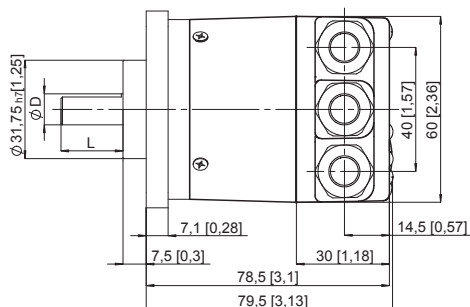


### Square flange, $\square$ 63.5 [2.5]

#### Flange type 5 and 7

(drawing with cable)

D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7



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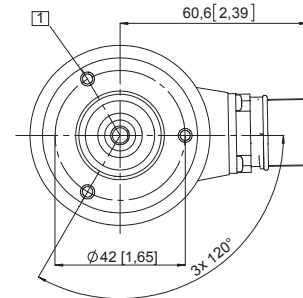
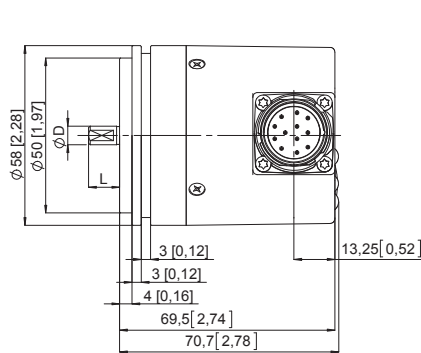
## Dimensions shaft version, with fixed connection

Dimensions in mm [inch]

### Synchro flange, $\varnothing 58$ [2.28] Flange type 2 and 4 (drawing with M23 connector)

- 1 M4, 6 [0.24] deep

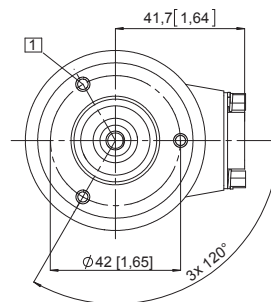
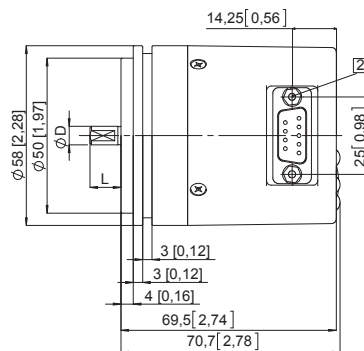
D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7



### Synchro flange, $\varnothing 58$ [2.28] Flange type 2 and 4 (drawing with Sub-D connector)

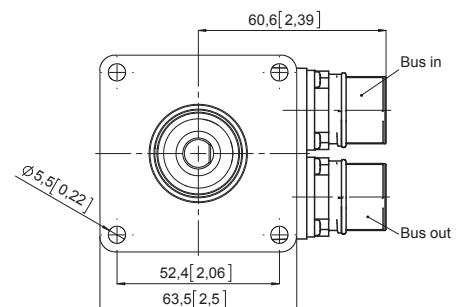
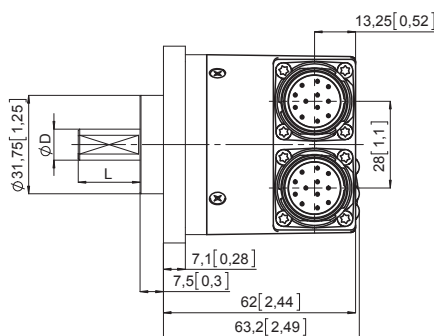
- 1 M4, 6 [0.24] deep
- 2 2 x 4/40 UNC; 3.0 [0.12] deep

D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7



### Square flange, $\square 63.5$ [2.5] Flange type 5 and 7 (drawing with 2 x M23 connector)

D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7



Absolute encoders  
multiturn

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mechanical multiturn, optical**

**Sendix 5868 / 5888 (shaft / hollow shaft)**

**CANopen/CANopenLift**

## Dimensions shaft version, with fixed connection

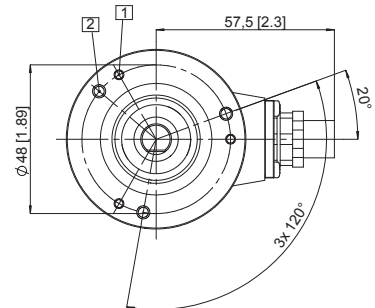
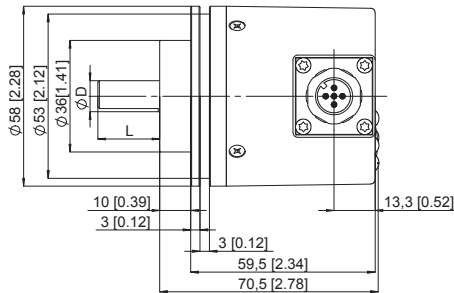
Dimensions in mm [inch]

### Clamping flange, $\varnothing$ 58 [2.28]

#### Flange type 1 and 3

(drawing with 1 x M12 connector)

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep



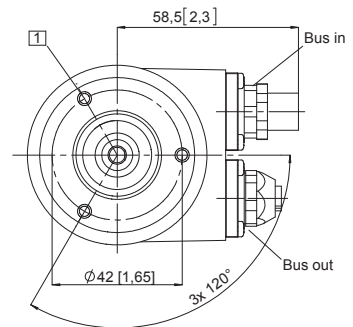
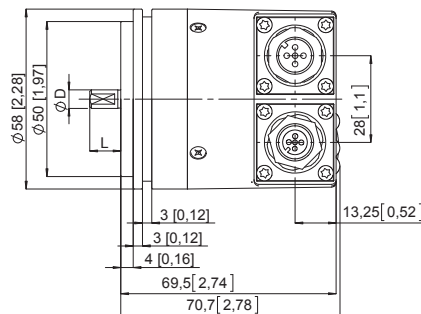
D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7

### Synchro flange, $\varnothing$ 58 [2.28]

#### Flange type 2 and 4

(drawing with M12 connector)

- 1 M4, 8 [0.32] deep



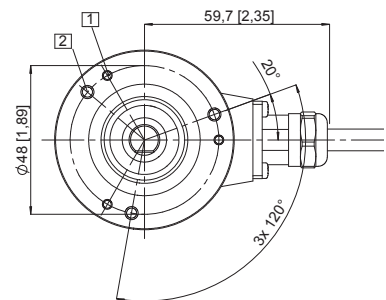
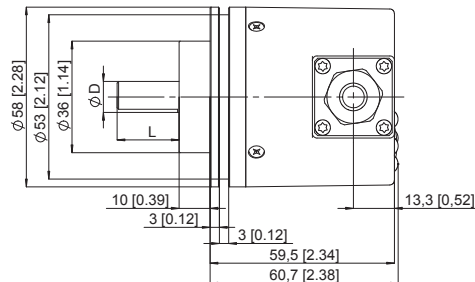
D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7

### Clamping flange, $\varnothing$ 58 [2.28]

#### Flange type 1 and 3

(drawing with cable)

- 1 3 x M3, 6 [0.24] deep
- 2 3 x M4, 8 [0.32] deep



D	L	Fit
6 [0.24]	10 [0.39]	h7
10 [0.39]	20 [0.79]	f7
1/4"	7/8"	h7
3/8"	7/8"	h7



# Absolute encoders – multiturn

**Standard  
mechanical multiturn, optical**

**Sendix 5868 / 5888 (shaft / hollow shaft)**

**CANopen/CANopenLift**

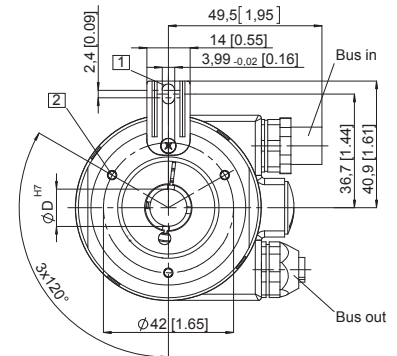
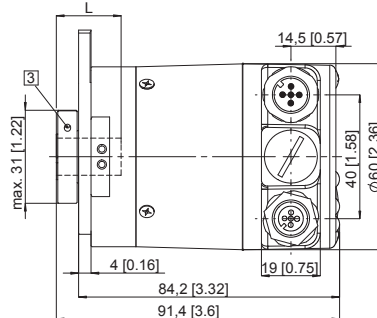
## Dimensions hollow shaft version (blind hollow shaft), with removable bus terminal cover

Dimensions in mm [inch]

### Flange with spring element, long Flange type 1 and 2

(drawing with 2 x M12 connector)

- 1 Torque stop slot, recommendation: cylindrical pin DIN 7,  $\varnothing 4$  [0.16]
  - 2 M3, 5.5 [0.21] deep
  - 3 Recommended torque for the clamping ring 0.6 Nm
- L: Insertion depth for blind hollow shaft: 30 [1.18]

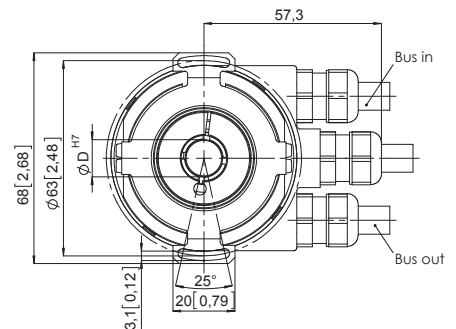
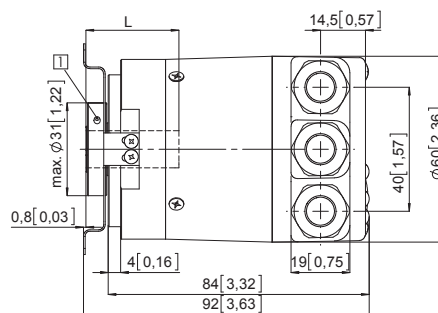


### Flange with stator coupling, $\varnothing 63$ [2.48]

#### Flange type 5 and 6

Pitch circle diameter for fixing screws 63 [2.48]  
(drawing with cable)

- 1 Recommended torque for the clamping ring 0.6 Nm
- L: Insertion depth for blind hollow shaft: 30 [1.18]

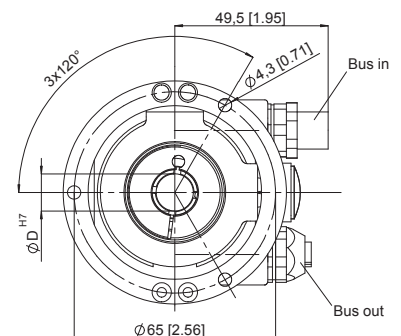
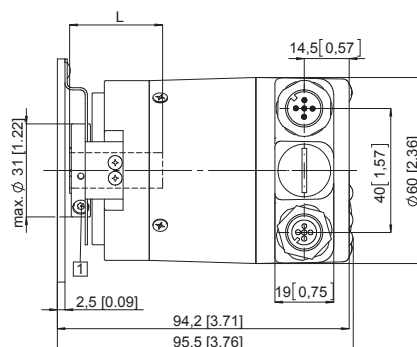


### Flange with stator coupling, $\varnothing 65$ [2.56]

#### Flange type 3 and 4

Pitch circle diameter for fixing screws 65 [2.56]  
(drawing with 2x M12 connector)

- 1 Recommended torque for the clamping ring 0.6 Nm
- L: Insertion depth for blind hollow shaft: 30 [1.18]



# Absolute encoders – multiturn

**Standard  
mechanical multiturn, optical**

**Sendix 5868 / 5888 (shaft / hollow shaft)**

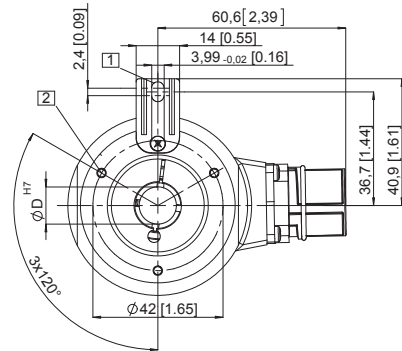
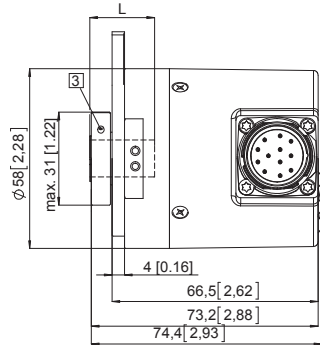
**CANopen/CANopenLift**

## Dimensions hollow shaft version (blind hollow shaft), with fixed connection

Dimensions in mm [inch]

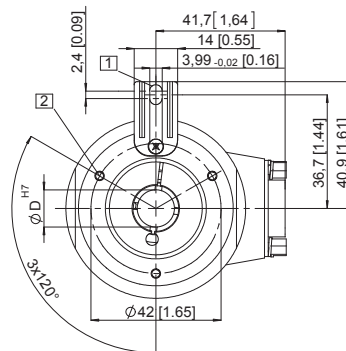
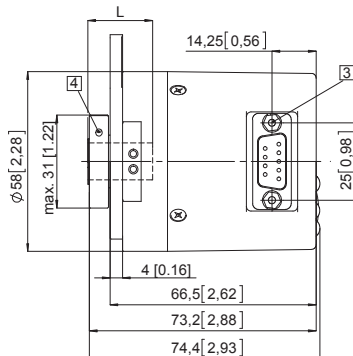
### Flange with spring element, long Flange type 1 and 2 (drawing with M23 connector)

- 1 Torque stop slot, recommendation: cylindrical pin DIN 7,  $\varnothing 4$  [0.16]
  - 2 M3, 5.5 [0.21] deep
  - 3 Recommended torque for the clamping ring 0.6 Nm
- L: Insertion depth for blind hollow shaft: 30 [1.18]



### Flange with spring element, long Flange type 1 and 2 (drawing with Sub-D connector)

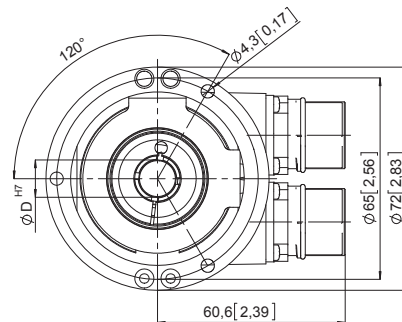
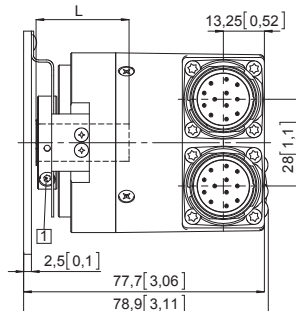
- 1 Torque stop slot, recommendation: cylindrical pin DIN 7,  $\varnothing 4$  [0.16]
  - 2 M3, 5.5 [0.21] deep
  - 3 2 x 4/40 UNC; 3.0 [0.21] deep
  - 4 Recommended torque for the clamping ring 0.6 Nm
- L: Insertion depth for blind hollow shaft: 30 [1.18]



### Flange with stator coupling, $\varnothing 65$ [2.56] Flange type 3 and 4

Pitch circle diameter for fixing screws 65 [2.56]  
(drawing with 2 x M23 connector)

- 1 Recommended torque for the clamping ring 0.6 Nm
- L: Insertion depth for blind hollow shaft: 30 [1.18]



# Absolute encoders – multiturn

<b>Standard mechanical multiturn, optical</b>	<b>Sendix 5868 / 5888 (shaft / hollow shaft)</b>	<b>CANopen/CANopenLift</b>
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## Dimensions hollow shaft version (blind hollow shaft), with fixed connection

Dimensions in mm [inch]

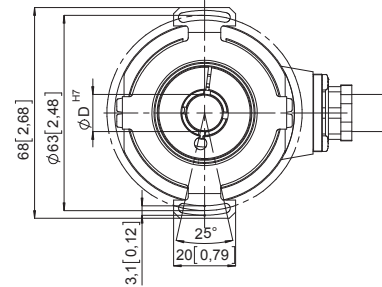
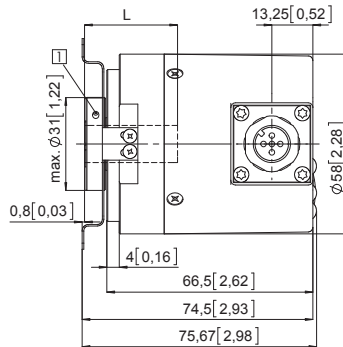
### Flange with stator coupling, $\varnothing$ 63 [2.48]

#### Flange type 5 and 6

Pitch circle diameter for fixing screws 63 [2.48]

(drawing with M12 connector)

- 1 Recommended torque for the clamping ring 0.6 Nm
- L: Insertion depth for blind hollow shaft: 30 [1.18]

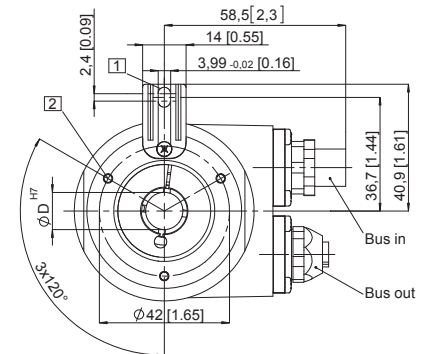
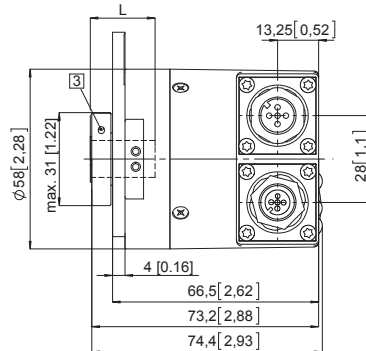


### Flange with spring element, long

#### Flange type 1 and 2

(drawing with 2 x M12 connector)

- 1 Torque stop slot, recommendation: cylindrical pin DIN 7,  $\varnothing$  4 [0.16]
- 2 M3, 5.5 [0.21] deep
- 3 Recommended torque for the clamping ring 0.6 Nm
- L: Insertion depth for blind hollow shaft: 30 [1.18]



### Flange with stator coupling, $\varnothing$ 65 [2.56]

#### Flange type 3 and 4

Pitch circle diameter for fixing screws 65 [2.56]

(drawing with cable)

- 1 Recommended torque for the clamping ring 0.6 Nm
- L: Insertion depth for blind hollow shaft: 30 [1.18]

